

Package ‘deriva’

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Title Tidy Drift Detection for Monitored Machine Learning Models

Version 0.1.0

Description Detects concept drift and data drift in streams produced by deployed machine learning models, using a tidy interface that composes with the 'tidymodels' ecosystem. Detectors are specified, fitted on a baseline period, and advanced over new batches of observations, returning tibbles annotated with warning and drift flags. A catalogue of 22 sequential drift detectors is provided. Error-based methods include the Drift Detection Method (DDM) of Gama et al. (2004) [<doi:10.1007/978-3-540-28645-5_29>](https://doi.org/10.1007/978-3-540-28645-5_29), the Early Drift Detection Method (EDDM) of Baena-Garcia et al. (2006), the Hoeffding's inequality based Drift Detection Methods (HDDM) of Frias-Blanco et al. (2015) [<doi:10.1109/TKDE.2014.2345382>](https://doi.org/10.1109/TKDE.2014.2345382), and the Exponentially Weighted Moving Average (EWMA) chart of Ross et al. (2012) [<doi:10.1016/j.patrec.2011.08.019>](https://doi.org/10.1016/j.patrec.2011.08.019). Distribution-based methods include Adaptive Windowing (ADWIN) of Bifet and Gavalda (2007) [<doi:10.1137/1.9781611972771.42>](https://doi.org/10.1137/1.9781611972771.42), Kolmogorov-Smirnov Windowing (KSWIN) of Raab et al. (2020) [<doi:10.1016/j.neucom.2019.11.111>](https://doi.org/10.1016/j.neucom.2019.11.111), and the Page-Hinkley test of Page (1954) [<doi:10.1093/biomet/41.1-2.100>](https://doi.org/10.1093/biomet/41.1-2.100).

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URL <https://github.com/bonijoao/deriva>

BugReports <https://github.com/bonijoao/deriva/issues>

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add_prediction_error	<i>Build a drift signal from model predictions</i>
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Description

Bridge from tidymodels: takes the output of augment() on a fitted workflow/model and adds a .error column — the signal drift detectors consume. Classification (factor/character truth): 0/1 mismatch against estimate (default column .pred_class). Regression (numeric truth): absolute error against estimate (default column .pred).

Usage

add_prediction_error(data, truth, estimate = NULL, ...)

Arguments

data	A data frame with truth and prediction columns.
truth	Unquoted name of the true outcome column.
estimate	Unquoted name of the prediction column. Defaults to .pred_class (classification) or .pred (regression), following tidymodels conventions.
...	Not used.

Value

data as a tibble with a `.error` column added.

Examples

```
d <- tibble::tibble(truth = c(1, 2, 3), .pred = c(1, 1, 5))
add_prediction_error(d, truth = truth)
```

advance	<i>Advance a fitted drift detector over a new batch</i>
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Description

Feeds a new batch of observations (any size, including 1 — stream mode) to the detector and returns a NEW fitted object with the engine state advanced and the annotated batch appended to the history. The original object is not modified. This is the only way to persist state; see [augment\(\)](#) for a read-only preview.

Usage

```
advance(object, ...)

## S3 method for class 'drift_detector_fit'
advance(object, new_data, ...)
```

Arguments

<code>object</code>	A <code>drift_detector_fit</code> .
<code>...</code>	Passed to methods.
<code>new_data</code>	A data frame with the new batch, in temporal order, containing the same signal column used in fit() .

Details

Why not `update()`: in the tidymodels ecosystem `update()` on a spec means "change hyperparameters", so `drift_detector` defines its own verb.

Value

A new `drift_detector_fit`.

Examples

```
base <- sim_drift_stream(n_pre = 100, n_post = 0, seed = 1)
f0 <- fit(drift_detector("ddm"), base, signal = error)
f1 <- advance(f0, sim_drift_stream(n_pre = 0, n_post = 50, seed = 2))
```

```
augment.drift_detector_fit
```

Annotated observations from a fitted drift detector

Description

With `new_data = NULL`, returns the accumulated history (baseline + advanced batches) annotated with `.warning`, `.drift` and `.phase`. With `new_data`, returns a READ-ONLY preview: the batch annotated from the current state, WITHOUT persisting it — use [advance\(\)](#) to persist.

Usage

```
## S3 method for class 'drift_detector_fit'
augment(x, new_data = NULL, ...)
```

Arguments

<code>x</code>	A <code>drift_detector_fit</code> .
<code>new_data</code>	Optional data frame with a new batch to preview.
<code>...</code>	Not used.

Value

A tibble.

Examples

```
base <- sim_drift_stream(n_pre = 100, n_post = 0, seed = 1)
f0 <- fit(drift_detector("ddm"), base, signal = error)
augment(f0)
```

```
autoplot.drift_detector_fit
```

Plot the monitored signal with drift markings

Description

Plots the running mean of the signal over the full history, with the baseline/stream boundary (labelled "training ends"), warning points (orange) and drift points (red vertical lines, the first one labelled with its index). Requires `ggplot2` (Suggests).

Usage

```
## S3 method for class 'drift_detector_fit'
autoplot(object, ...)
```

Arguments

object	A drift_detector_fit.
...	Not used.

Value

A ggplot object.

detect_drift	<i>Detect drift in a signal column (one-shot shortcut)</i>
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Description

Layer-3 convenience: runs a detector over an existing signal column and returns the data annotated with `.warning` / `.drift`. For an explicit baseline and persistent state, use the full object path: `drift_detector() + fit() + advance()`.

Usage

```
detect_drift(data, .col, method = "ddm", ...)
```

Arguments

data	A data frame in temporal order.
.col	Unquoted name of the signal column.
method	Name of a registered method (default "ddm").
...	Hyperparameters forwarded to <code>drift_detector()</code> .

Details

For "ddm", the warm-up is governed by `min_instances`: the first `min_instances - 1` observations get NA flags.

Value

data as a tibble with `.warning` and `.drift` columns added.

Examples

```
s <- sim_drift_stream(seed = 42)
detect_drift(s, .col = error, method = "ddm")
```

drift_detector	<i>Specify a drift detector</i>
----------------	---------------------------------

Description

Creates an inert detector specification (analogous to a parsnip model spec). Nothing is computed until `fit()` is called on a baseline period.

Usage

```
drift_detector(method = "ddm", ...)
```

Arguments

method	Name of a registered detection method, e.g. "ddm".
...	Method hyperparameters overriding the defaults (e.g. min_instances = 50 for "ddm"). Unknown parameters error.

Value

A drift_detector specification object.

Examples

```
drift_detector("ddm", min_instances = 50)
```

fit.drift_detector	<i>Fit a drift detector on a baseline period</i>
--------------------	--

Description

Runs the detector over the baseline data — the period where the monitored model is considered stable — so it learns the reference ("normal") level. The returned object is immutable: feed new batches with `advance()`.

Usage

```
## S3 method for class 'drift_detector'
fit(object, data, signal, ...)
```

Arguments

object	A <code>drift_detector()</code> specification.
data	A data frame with the baseline period, in temporal order.
signal	Unquoted name of the signal column (0/1 errors for error-based methods such as "ddm").
...	Not used.

Value

A drift_detector_fit object.

Examples

```
base <- sim_drift_stream(n_pre = 100, n_post = 0, seed = 1)
fit(drift_detector("ddm"), base, signal = error)
```

```
glance.drift_detector_fit
```

One-row summary of a fitted detector

Description

One-row summary of a fitted detector

Usage

```
## S3 method for class 'drift_detector_fit'
glance(x, ...)
```

Arguments

`x` A drift_detector_fit.
`...` Not used.

Value

A 1-row tibble: method, n_obs, n_warning, n_drift, first_drift (NA if no drift detected).

```
sim_dist_stream
```

Simulate a continuous stream with a known distribution-shift point

Description

Generates a numeric stream drawn from $N(\text{mean_pre}, \text{sd_pre})$ for the first `n_pre` observations and $N(\text{mean_post}, \text{sd_post})$ afterwards. Companion to [sim_drift_stream\(\)](#) for distribution-based detectors (e.g. "kswin").

Usage

```
sim_dist_stream(
  n_pre = 500,
  n_post = 500,
  mean_pre = 0,
  mean_post = 3,
  sd_pre = 1,
  sd_post = 1,
  seed = NULL
)
```

Arguments

n_pre, n_post Observations before / after the shift point.
 mean_pre, mean_post Means before / after the shift.
 sd_pre, sd_post Standard deviations before / after the shift.
 seed Optional integer for set.seed().

Value

A tibble with t (index), value (numeric) and drift_true (logical: TRUE after the shift point).

Examples

```
sim_dist_stream(n_pre = 100, n_post = 100, mean_post = 3, seed = 42)
```

sim_drift_stream	<i>Simulate a binary error stream with a known drift point</i>
------------------	--

Description

Generates a stream of 0/1 classifier errors whose error rate jumps from p_pre to p_post after n_pre observations. Useful for testing and validating drift detectors against a known ground truth.

Usage

```
sim_drift_stream(
  n_pre = 500,
  n_post = 500,
  p_pre = 0.05,
  p_post = 0.3,
  seed = NULL
)
```

Arguments

n_pre, n_post	Number of observations before / after the drift point.
p_pre, p_post	Error probability before / after the drift point.
seed	Optional integer; if supplied, set.seed() is called for reproducibility.

Value

A tibble with columns t (index), error (0/1) and drift_true (logical ground truth: TRUE after the drift point).

Examples

```
sim_drift_stream(n_pre = 100, n_post = 100, seed = 42)
```

```
tidy.drift_detector_fit
```

Drift points of a fitted detector

Description

Drift points of a fitted detector

Usage

```
## S3 method for class 'drift_detector_fit'
tidy(x, ...)
```

Arguments

x	A drift_detector_fit.
...	Not used.

Value

A tibble with one row per detected drift: index (position in the history) and phase.

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